

# 3. Boundary value problems

Modeling with ODEs

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# Basic concepts

- **First-order ODEs**

- Let  $\Omega \subset \mathbb{R}^2$ ,  $F: \Omega \rightarrow \mathbb{R}$  a continuous function. Then:

$$y'(t) = F(t, y(t))$$

is a first-order ODE in the unknown function  $y(t)$ . A function  $y: [a, b] \rightarrow \mathbb{R}$  is called *a solution of the ODE* if this equation is satisfied for every  $t \in [a, b] \subset \mathbb{R}$

# Basic concepts

- **Autonomous:** the ODE does not depend on  $t$  explicitly.
  - $y' = F(y(t)) \rightarrow$  *Autonomous*. E.g.  $y' = y$
  - $y' = F(y(t), t) \rightarrow$  *Non autonomous*. E.g.  $y' = y \cdot e^{-t}$

# Basic concepts

- **Boundary value problems**

Let  $\Omega \subset \mathbb{R}^2$ ,  $F: \Omega \rightarrow \mathbb{R}$  a continuous function and  $y_0, y_1 \in \mathbb{R}$ . Then:

$$y''(t) = F(t, y(t), y'(t))$$

$$y(a) = y_0$$

$$y(b) = y_1$$

is an *boundary value problem* for the ODE equation. A function  $y: [a, b] \rightarrow \mathbb{R}$  is called *a solution of the ODE* if all equations are satisfied for every  $t \in [a, b] \subset \mathbb{R}$

# Basic concepts

- **Linear versus nonlinear**

- A linear ODE is a linear polynomial in the unknown function

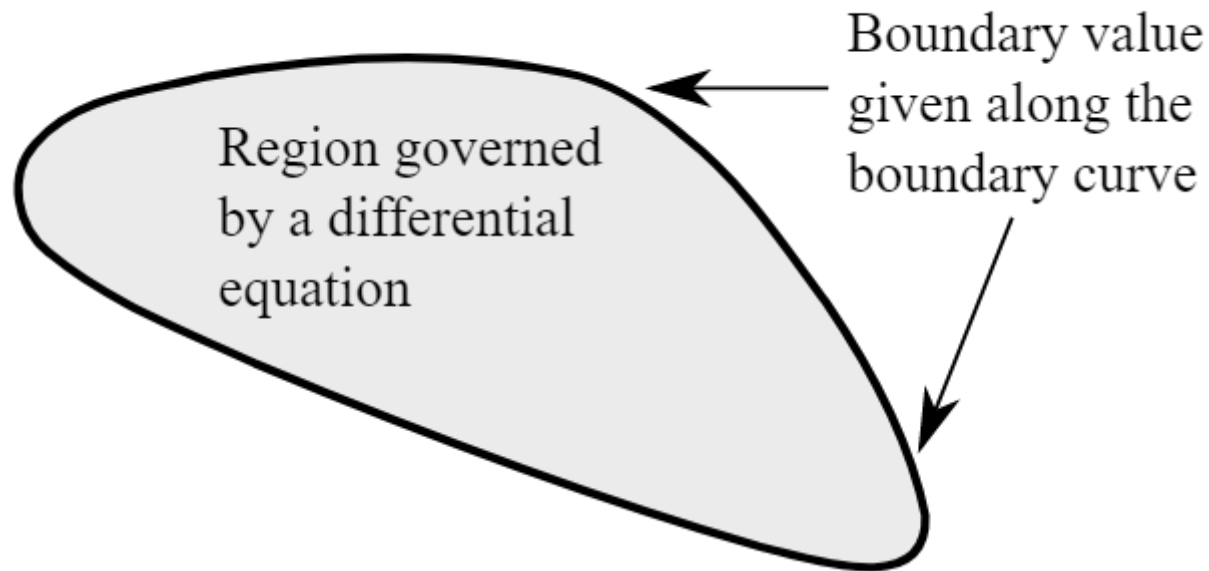
$$\begin{aligned} y^{(n)} &= b(x) + a_0(x) \cdot y + a_1(x) \cdot y' + \cdots + a_{n-1}(x) \cdot y^{(n-1)} \\ &= b(x) + \sum_{i=0}^{n-1} a_i(x) \cdot y^{(i)} \end{aligned}$$

- Example:
  - Body temperature
  - Clock alarm temperature

# Basic concepts

- **Closed form vs. Numerical solutions**
  - Closed form: (otherwise known as analytical solution) Is a solution of the ODE in terms of “well-known” equations. Most ODEs cannot be solved in this way.
  - Numerical form: Appropriate computer algorithms are used to obtain approximations of the ODE solutions.

# Boundary value problems



Boundary Value Problem. (Image source: [Wikipedia](#))

# Boundary value problems

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# Definitions of derivative

- $\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f(t+\Delta t) - f(t)}{\Delta t} \rightarrow$  Forward Euler
- $\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f(t) - f(t-\Delta t)}{\Delta t} \rightarrow$  Backward Euler
- $\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f\left(t+\frac{\Delta t}{2}\right) - f\left(t-\frac{\Delta t}{2}\right)}{\Delta t} \rightarrow$  Central differences

# Boundary value problems

$$\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f\left(t + \frac{\Delta t}{2}\right) - f\left(t - \frac{\Delta t}{2}\right)}{\Delta t}$$

If  $\Delta t$  is close to 0, we can approximate the derivative to:

$$\frac{df(t)}{dt} \approx \frac{f\left(t + \frac{\Delta t}{2}\right) - f\left(t - \frac{\Delta t}{2}\right)}{\Delta t}$$

In boundary value problems we usually need the second derivative

$$\frac{d^2 f(t)}{dt^2} \approx \frac{f'\left(t + \frac{\Delta t}{2}\right) - f'\left(t - \frac{\Delta t}{2}\right)}{\Delta t}$$

# Boundary value problems

$$f''(t) = \frac{d^2 f(t)}{dt^2} \approx \frac{f' \left( t + \frac{\Delta t}{2} \right) - f' \left( t - \frac{\Delta t}{2} \right)}{\Delta t}$$

We can calculate both derivatives:

$$f' \left( t + \frac{\Delta t}{2} \right) = \frac{df \left( t + \frac{\Delta t}{2} \right)}{dt} \approx \frac{f(t + \Delta t) - f(t)}{\Delta t}$$

$$f' \left( t - \frac{\Delta t}{2} \right) = \frac{df \left( t - \frac{\Delta t}{2} \right)}{dt} \approx \frac{f(t) - f(t - \Delta t)}{\Delta t}$$

# Boundary value problems

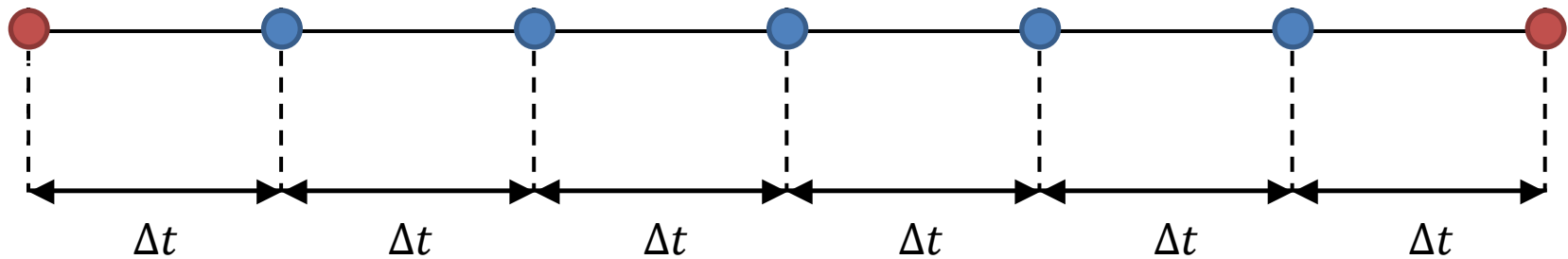
We can join both expressions:

$$\begin{aligned} f''(t) &= \frac{\frac{f(t + \Delta t) - f(t)}{\Delta t} - \frac{f(t) - f(t - \Delta t)}{\Delta t}}{\Delta t} = \\ &= \frac{f(t + \Delta t) - f(t) - f(t) + f(t - \Delta t)}{\Delta t^2} \\ &= \frac{f(t + \Delta t) + f(t - \Delta t) - 2f(t)}{\Delta t^2} \end{aligned}$$

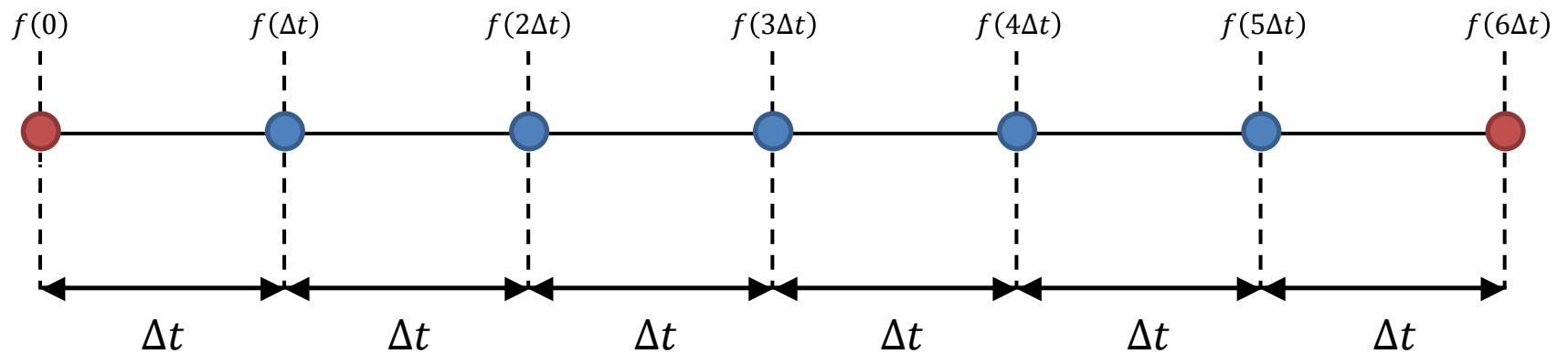
# Boundary value problems



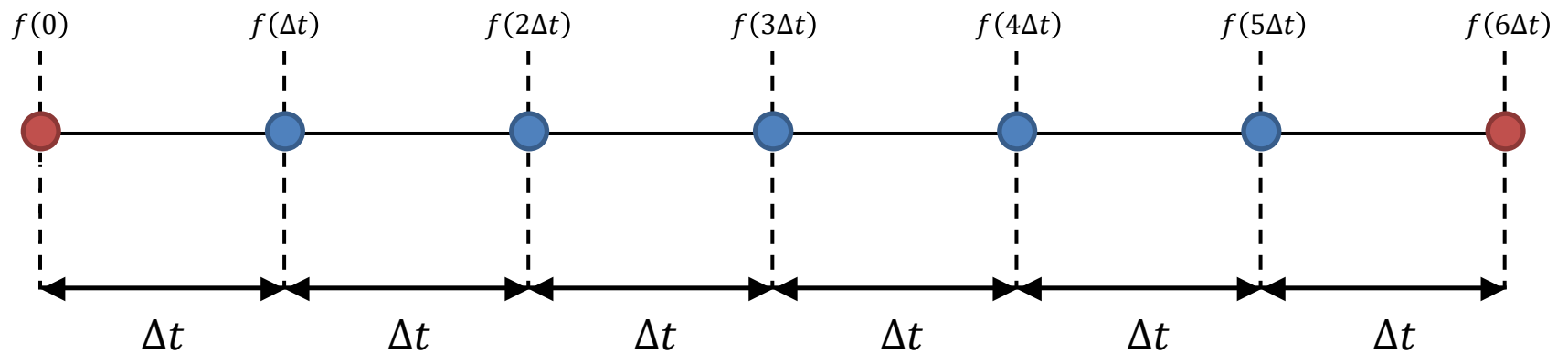
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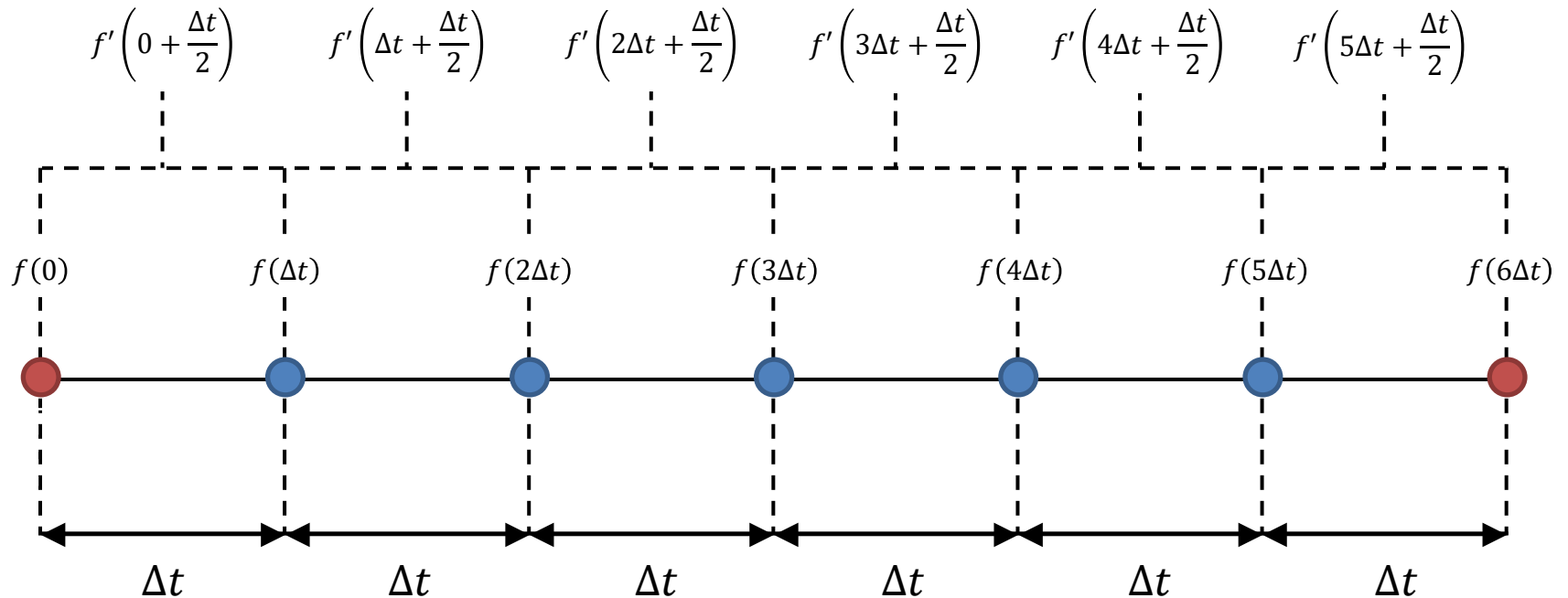


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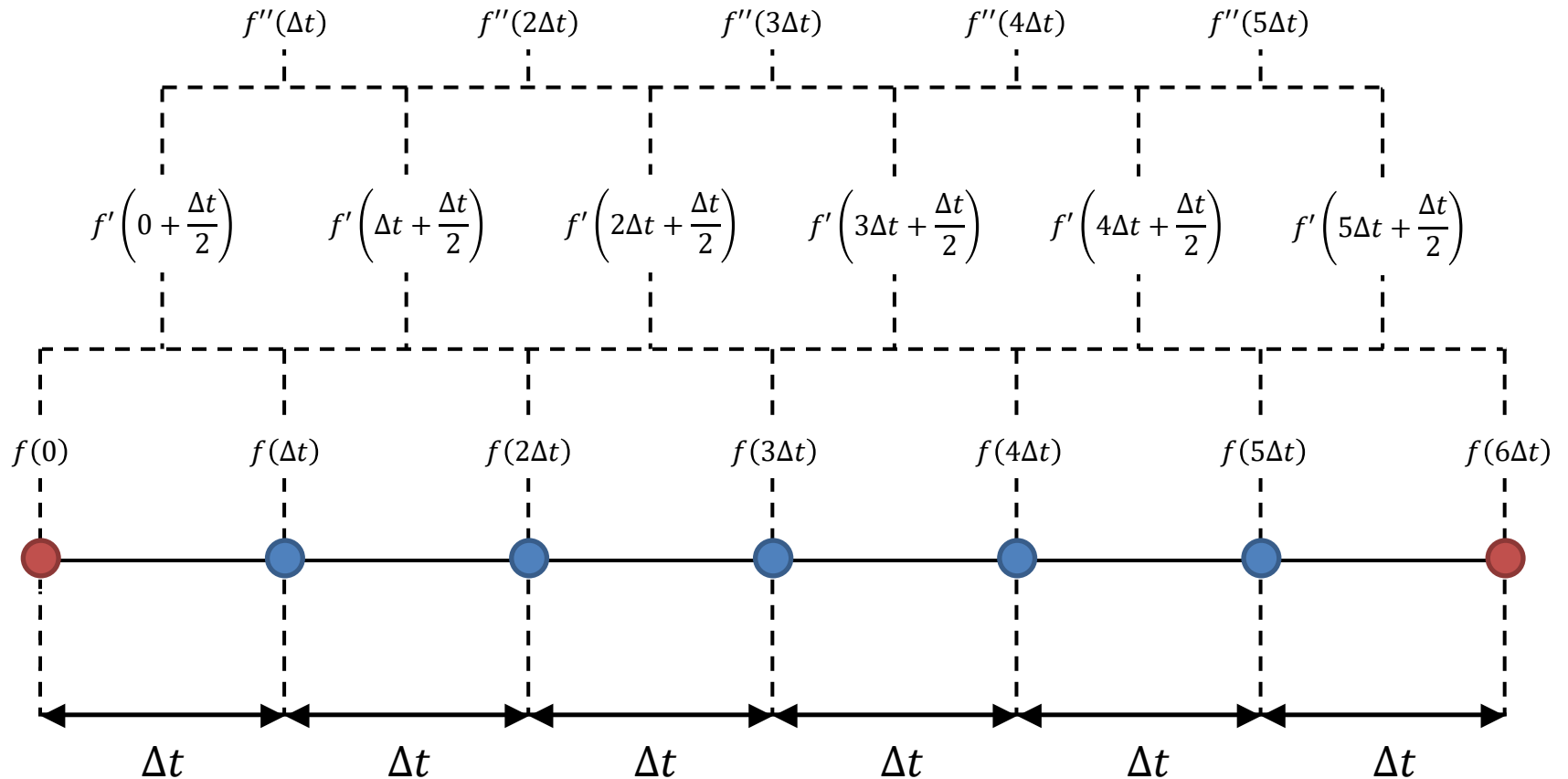




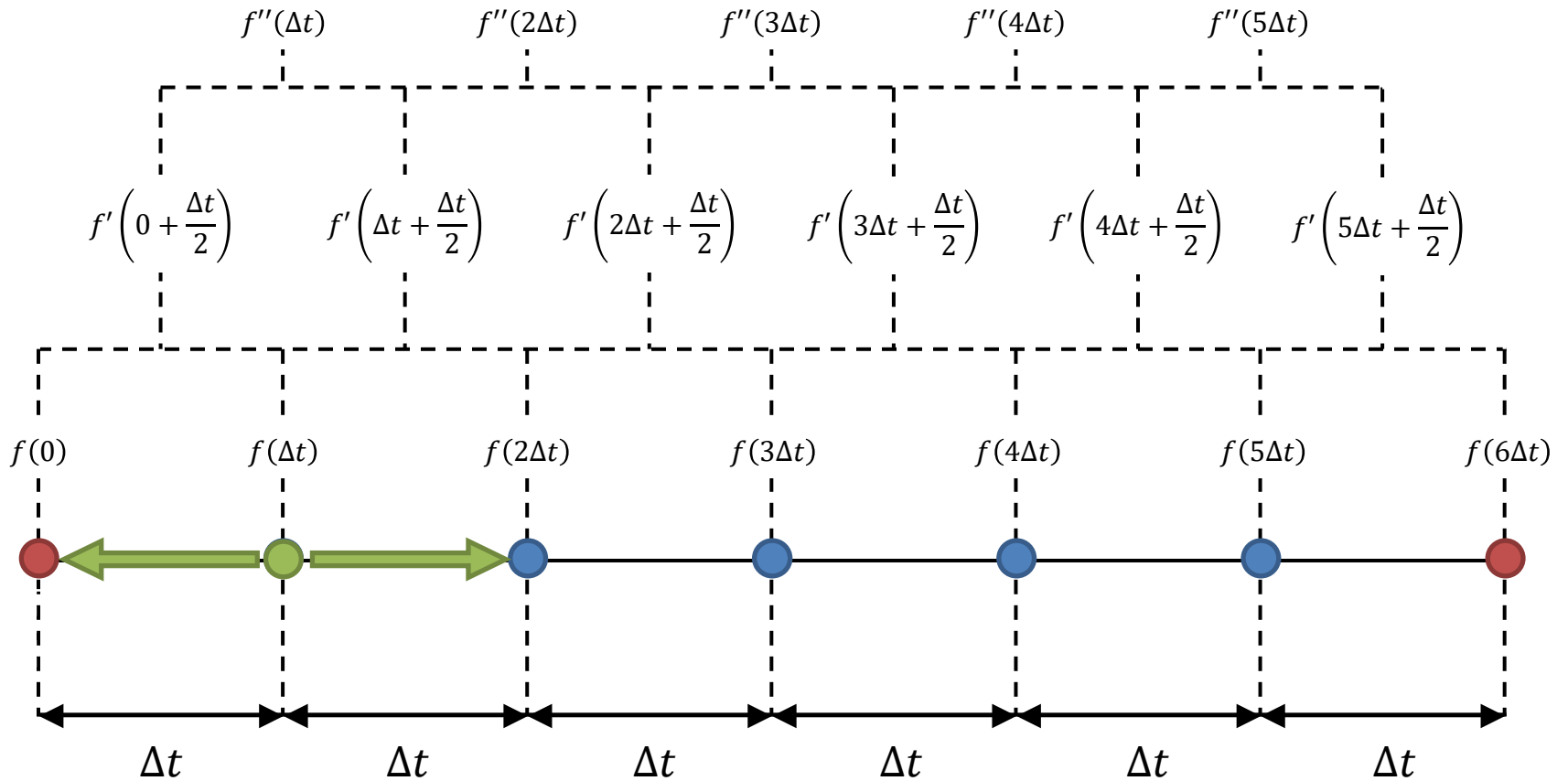
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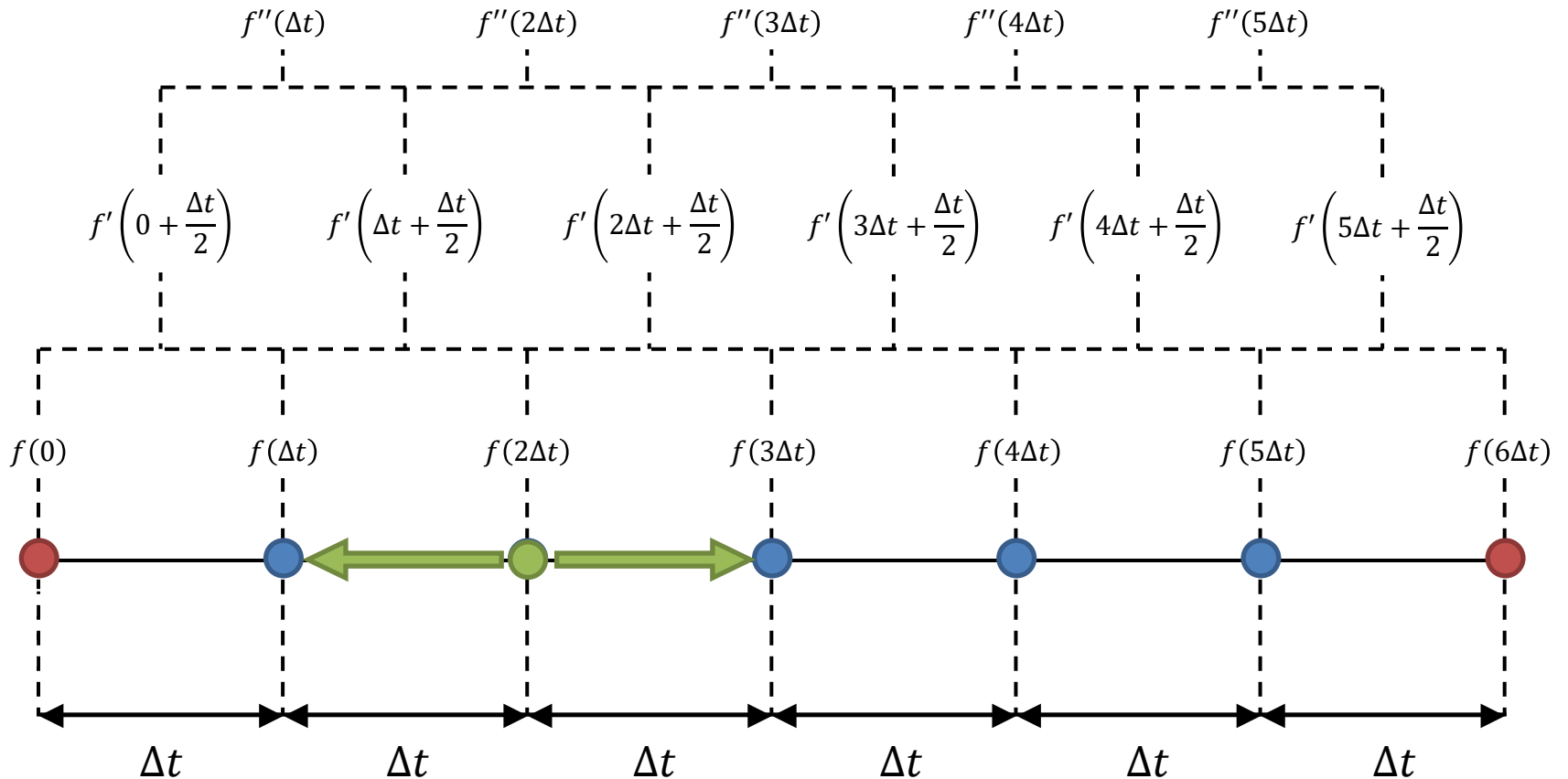
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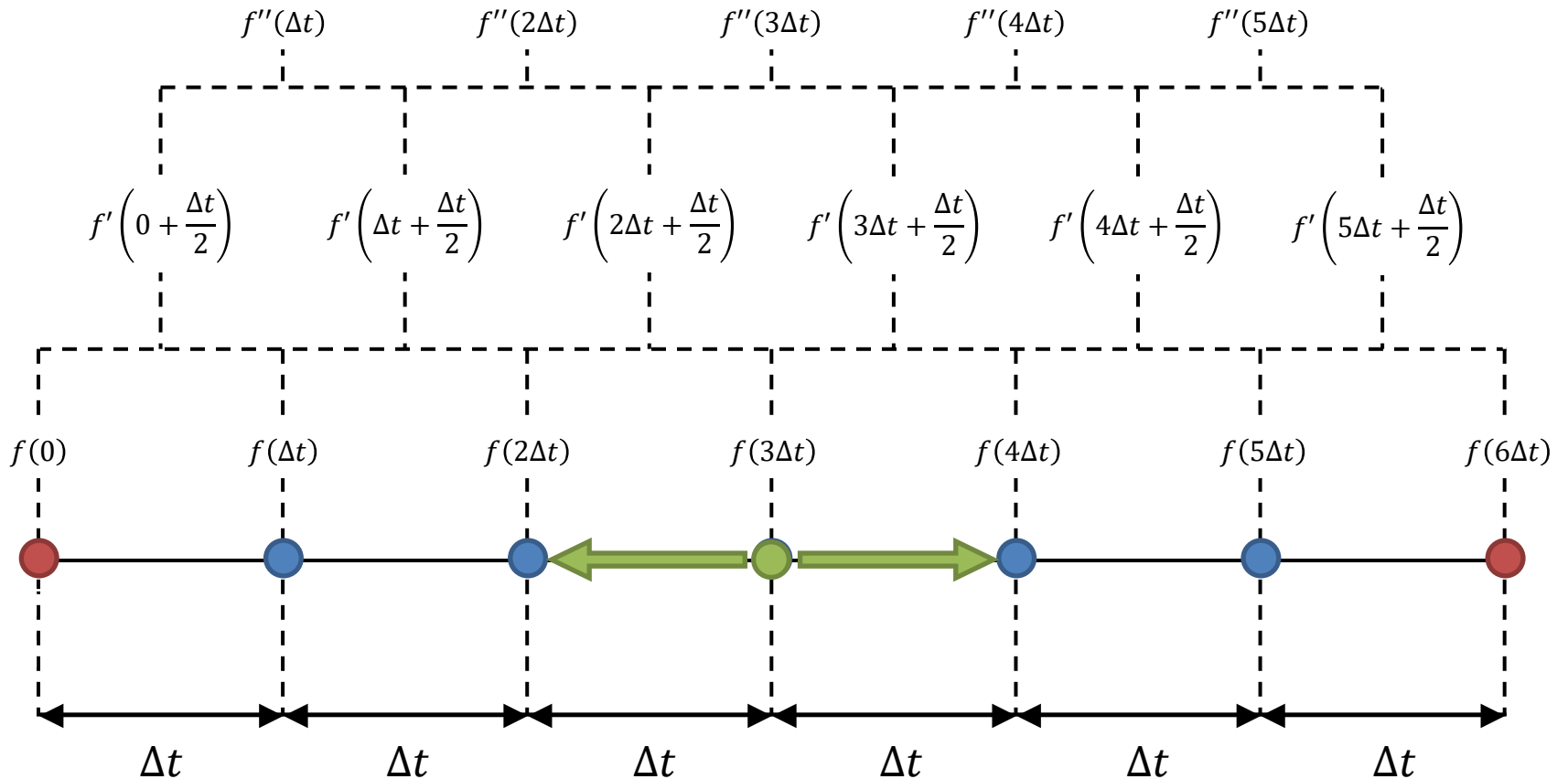
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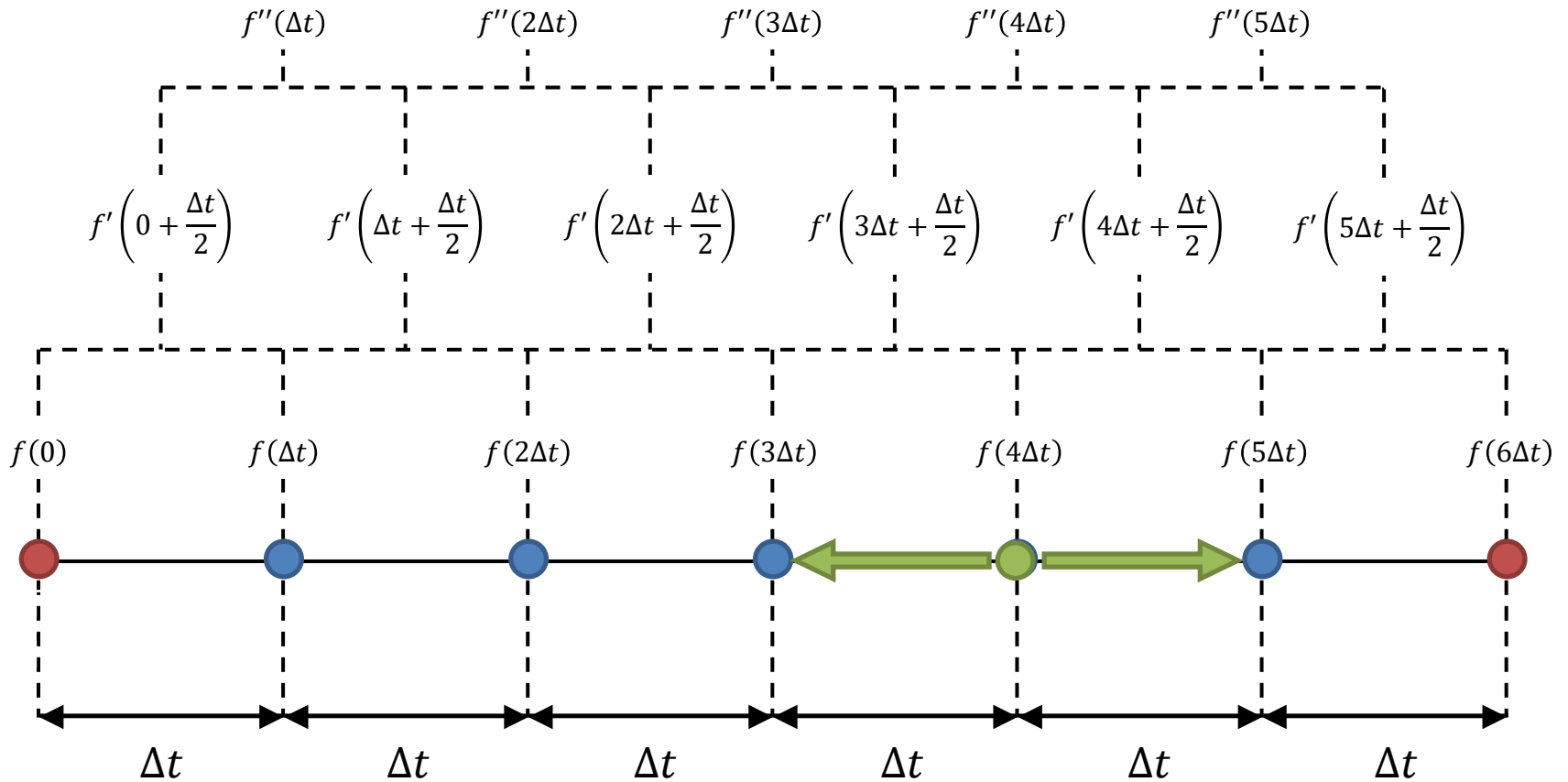
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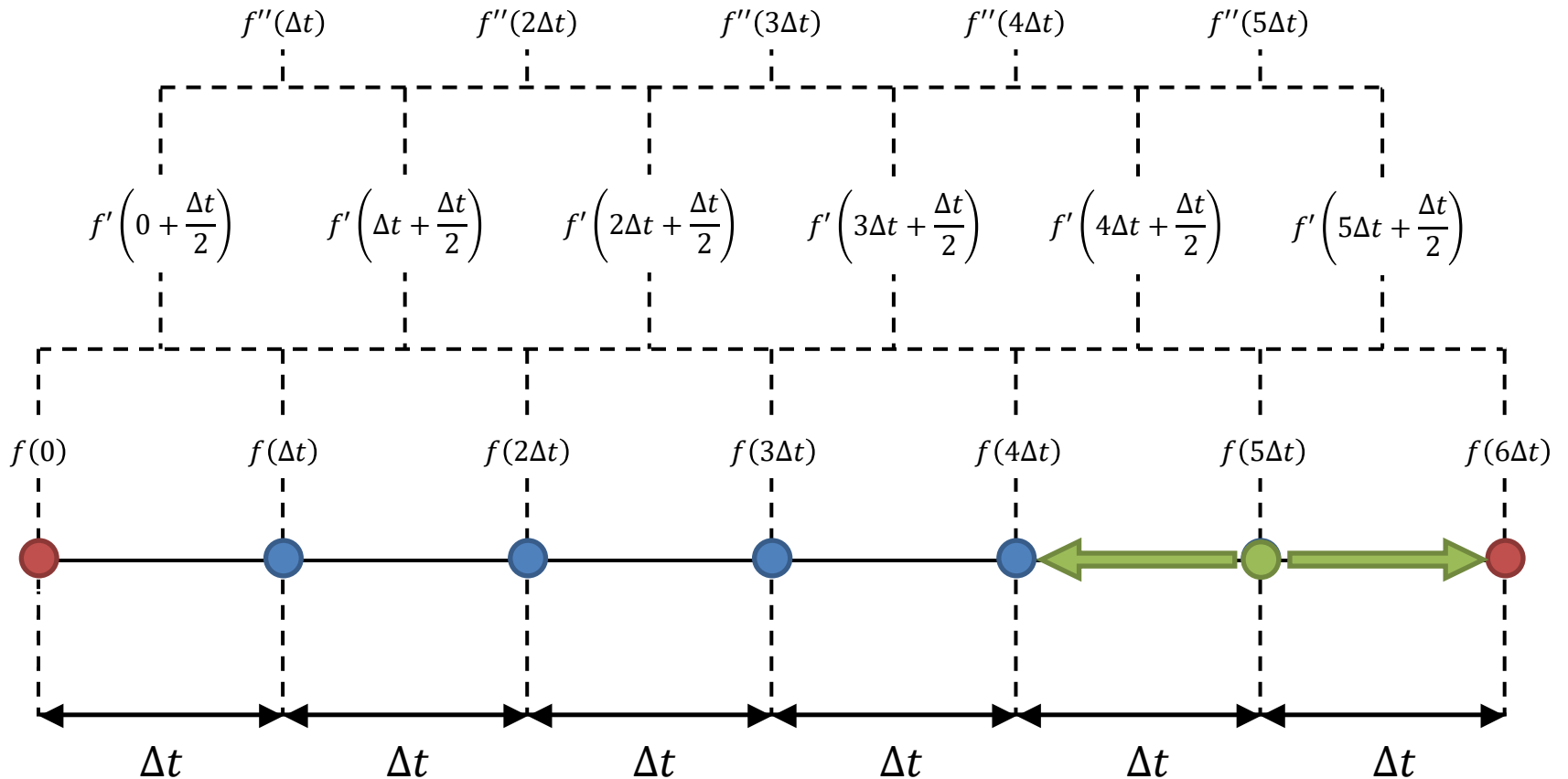
# Boundary value problems



# Boundary value problems



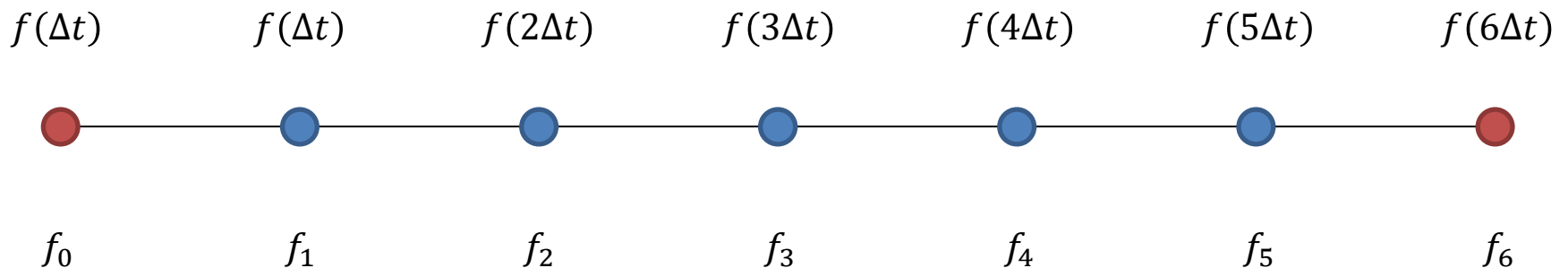
# Boundary value problems



# Boundary value problems

- Simplification of the notation:

$$f(n \cdot \Delta t) = f_n$$





# Boundary value problems

- System of equations:
  - For each unknown ( $f_i$ ) we can obtain an equation:

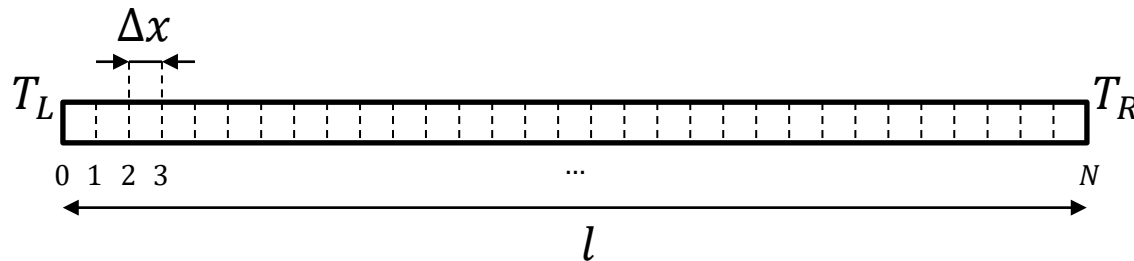
$$f_i'' = \frac{f_{i-1} + f_{i+1} - 2f_i}{\Delta t^2} \Rightarrow f_{i-1} - 2f_i + f_{i+1} = \Delta t^2 \cdot f_i''$$

- The second derivative ( $f_i''$ ) is defined in the ODE
- We can get as many equations as unknowns

# The 1D stationary Heat Equation

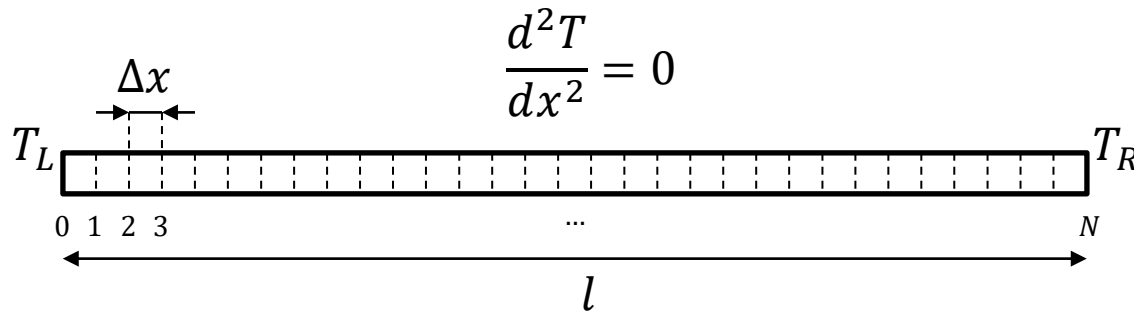
$$\frac{\partial T}{\partial t} = \kappa \frac{\partial^2 T}{\partial x^2}$$

- Under steady-state conditions:  $\frac{\partial T}{\partial t} = 0 \Rightarrow \frac{d^2 T}{dx^2} = 0$



- Boundary conditions
  - $T(0) = T_0 = T_L$
  - $T(l) = T_N = T_R$

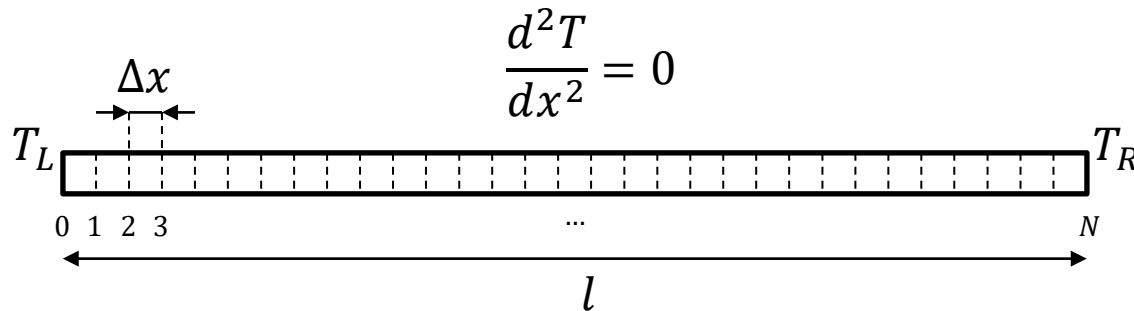
# The 1D stationary Heat Equation



- If  $N=3$  we have 4 equations:
  - $T(0) = T_0 = T_L$
  - $T(\Delta x) = T_1: T_0 - 2T_1 + T_2 = 0$
  - $T(2\Delta x) = T_2: T_1 - 2T_2 + T_3 = 0$
  - $T(l) = T_3 = T_R$
- As a product of matrices

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} T_0 \\ T_1 \\ T_2 \\ T_3 \end{pmatrix} = \begin{pmatrix} T_L \\ 0 \\ 0 \\ T_R \end{pmatrix}$$

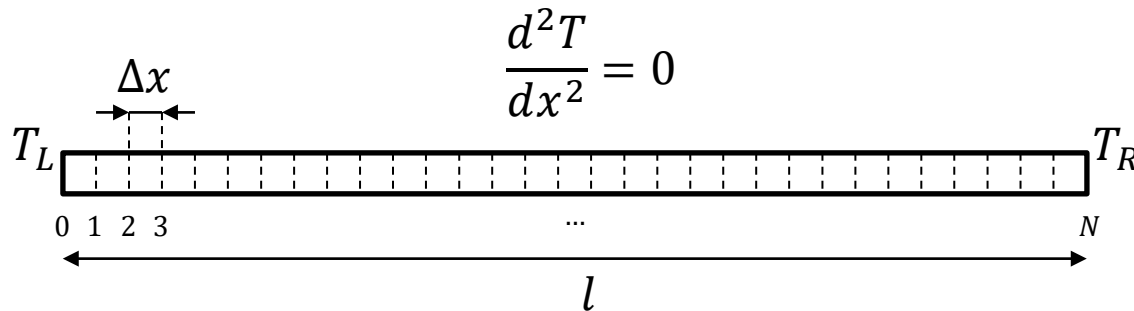
# The 1D stationary Heat Equation



- We can extend it to the N+1 positions

$$\begin{pmatrix}
 1 & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 0 \\
 1 & -2 & 1 & 0 & 0 & \dots & 0 & 0 & 0 \\
 0 & 1 & -2 & 1 & 0 & \dots & 0 & 0 & 0 \\
 0 & 0 & 1 & -2 & 1 & \dots & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & -2 & \dots & 0 & 0 & 0 \\
 \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\
 0 & 0 & 0 & 0 & 0 & \dots & -2 & 1 & 0 \\
 0 & 0 & 0 & 0 & 0 & \dots & 1 & -2 & 1 \\
 0 & 0 & 0 & 0 & 0 & \dots & 0 & 0 & 1
 \end{pmatrix} \cdot \begin{pmatrix} T_0 \\ T_1 \\ T_2 \\ T_3 \\ T_4 \\ \vdots \\ T_{N-2} \\ T_{N-1} \\ T_N \end{pmatrix} = \begin{pmatrix} T_L \\ 0 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \\ 0 \\ T_R \end{pmatrix}$$

# The 1D stationary Heat Equation



- Solving the system:

$$A \cdot T = b \Rightarrow T = A^{-1} \cdot b$$

# Example

- The gravity problem with boundary values:
  - In the instant 0, a ball is at a high of 100 meters.
  - Five seconds later, the ball touch the ground.
  - Can you calculate how high the ball was at each instant of time?

$$\frac{d^2h}{dt^2} = g$$

$$h(0) = 100$$

$$h(5) = 0$$

- Initial value problems

- Explicit:

$$\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f(t+\Delta t) - f(t)}{\Delta t} \rightarrow f(t + \Delta t) \approx f(t) + \Delta t \cdot f'(t) \text{ (Forward Euler)}$$

- Implicit

$$\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f(t) - f(t-\Delta t)}{\Delta t} \rightarrow f(t + \Delta t) \approx f(t) + \Delta t \cdot f'(t + \Delta t) \text{ (Backward Euler)}$$

- Boundary value problems:

$$\frac{df(t)}{dt} = \lim_{\Delta t \rightarrow 0} \frac{f\left(t+\frac{\Delta t}{2}\right) - f\left(t-\frac{\Delta t}{2}\right)}{\Delta t} \rightarrow f''(t) \approx \frac{f(t-\Delta t) - 2f(t) + f(t+\Delta t)}{\Delta t^2} \text{ (Central Differences)}$$

- For all the problems are other methods of higher order
- We have learned the most easy and typical ones for each problem
- You can try to use the different techniques in the other problems:
  - E.g.: FE for the boundary value problem.



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